

# RB Flat Displacement Sensor



## Technical Characteristics

- Non-wear, non-contact measurement method
- Rugged and fully enclosed design
- Linear measurement, absolute position output
- Low power consumption design effectively reduces system heating
- Sealing grade up to IP67
- Multiple signal type optional: Analog、SSI、CANopen

C C Product Parameters

• Input

Measurement data	Position Magnet ring
Stroke length	50mm~5500mm , customized according to customer's needs
Number of measurements	1

• Output

Interface	Analog、SSI、CANopen
Resolution	Analog: 16-bit D/A or 0.0015% of full scale (min. 1μm)
	Digital quantity: 1 / 2 / 5 / 10 / 20 / 40 / 50 / 100 μm
Nonlinearity	< ± 0.01% of full scale, Min. ± 50μm
Repetition accuracy	< ± 0.001% of full scale, Min. ± 1μm
Hysteresis	< 10μm
Update time	1KHz (range≤1m)      500Hz (1m<range≤2m)
	250Hz (2m<range≤3m) , customizable
Temperature coefficient	<30ppm/℃

• Operating conditions

Magnet ring velocity	Arbitrary
Protection level	IP67
Operating temperature	-40℃ ~ +85℃
Humidity/dew point	100%, relative humidity
Shock index	GB/T2423.5 100g(6ms)
Vibration index	GB/T2423.10 20g/10~2000Hz
EMC test	GB/T17626.2/3/4/6/8, Grade 4/3/4/3/3, Class A, CE Certification

• Electrical connection

Input voltage	+24Vdc±20%
operating current	< 100mA ( varying with range)
Polarity protection	Max.-30Vdc
Overvoltage protection	Max.36Vdc
Insulation resistance	> 10MΩ
Insulation strength	500V

• Structure and materials

Electronic bin	304 stainless steel
Measuring rod	304 stainless steel
Outer tube pressure resistance	35MPa (continuous)/70MPa (peak) or 350ba (continuous)/700ba ( peak)
Position magnet	Standard magnetic ring and various ring magnets
Mounting thread	6 M6X16 screws, M18×1.5、 M20×1.5 (Customizable)
Installation direction	Any direction
Connection type	Cable outlet or connector

## RB Flat Displacement Sensor

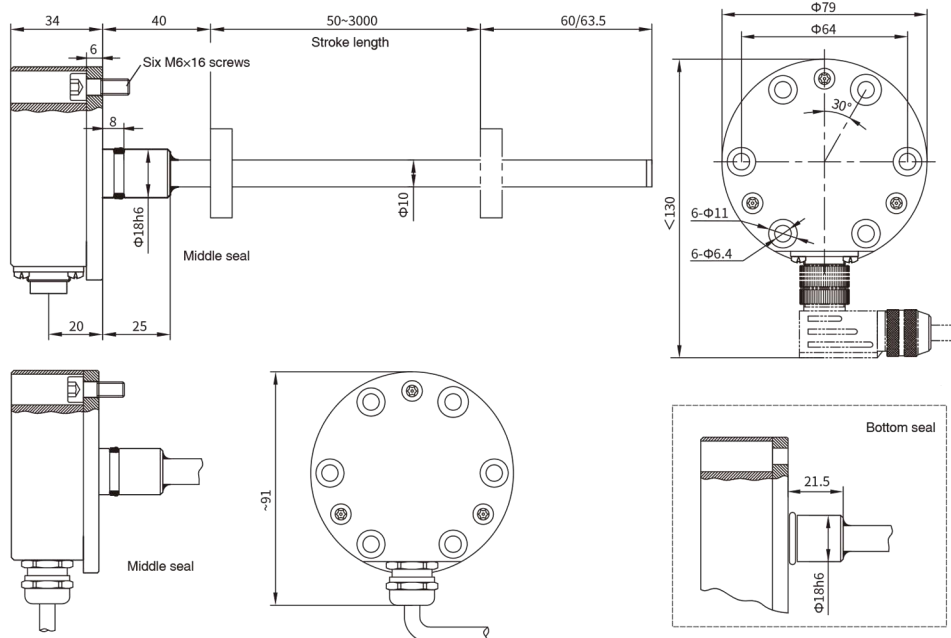
### A a Installation and Instructions for use

#### ● Output characteristic

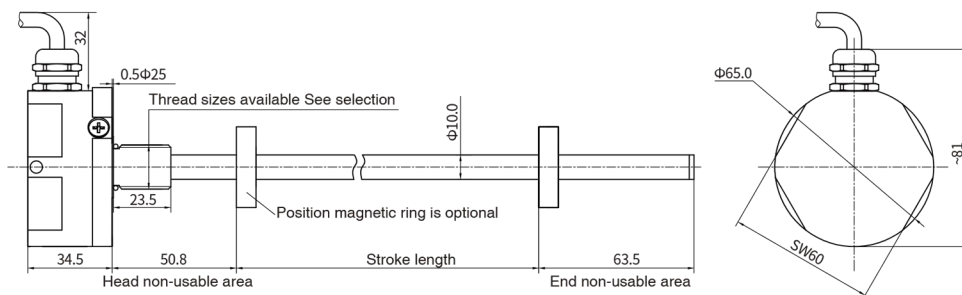
RB series sensors have high-strength protective shell and high working temperature, and are durable, which can provide users with continuous, reliable and real-time displacement signals in harsh environment. The sensor has a completely stainless steel shell. It is suitable for installing in hydraulic cylinder and measuring the stroke of piston, and is widely used in energy and mining industries. Thanks to its flat and compact design, the sensor is very suitable for cylinder installation in narrow space.

#### ● Installation dimensions

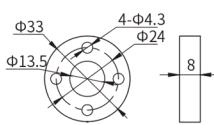
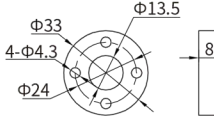
##### Tight pressure seal type



##### External thread type(Only cable outlet mode are supported)



### C c Commonly used accessories

Accessory name/ model	Dimensions	Accessory name/ model	Dimensions
Standard magnetic ring Order No.: 211501		Standard Magnet ring Kit Order No.: 288501	
		Includes: 1 Magnet, 1 gasket, 4 screws with spring washer	

● Note: Please refer to "Magnet Ring Selection" for details of magnet ring kit and other models

# RB Flat Displacement Sensor

DISPLACEMENT SENSORS

## X Selection Guide-Analog Quantity

R	B	-	M					-			-					-					-		
01	02		03	04	05	06	07		08	09		10	11	12	13		14	15	16	17		18	19

01 - 02	Sensor shell form	14 - 17	Signal output mode
R B	Compact sealing installation	14 - 15	Output form and direction
03 - 07	Stroke length	A 0	Current output, 4 ~ 20mA
	Four digits, less than four digits are preceded by zero, M means metric system, unit mm	A 1	Current output, 20 ~ 4mA
		A 2	Current output, 0 ~ 20mA
		A 3	Current output, 20 ~ 0mA
08 - 09	Installation form	V 0	Voltage output, 0 ~ 10V
S 1	Bottom seal	V 1	Voltage output, 10 ~ 0V
S 2	Middle seal	V 2	Voltage output, -10 ~ +10V
S A	M18X1.5 measuring rod diameter 10mm, 304 material	V 3	Voltage output, +10 ~ -10V
S B	M20X1.5 measuring rod diameter 10mm, 304 material	V 4	Voltage output, 0 ~ 5V
		V 5	Voltage output, 5 ~ 0V
10 - 13	Connection form	V 6	Voltage output, -5 ~ +5V
10 - 11	For cable outlet	V 7	Voltage output, +5 ~ -5V
D H	PUR sheath, orange,-20~90℃, end scattered, cable color 1	16	Number of magnet ring
D U	PVC sheath, orange,-20~105℃, end scattered, cable color 2	1	Single magnet ring
D B	PVC sheath, orange,-20~105℃, end scattered, cable color 3	17	No magnet ring state
D I	PUR sheath, orange,-20~90℃, end with 6-pin connector	A	Keep the original value
D V	PVC sheath, orange,-20~105℃, end with 6-pin connector	B	Max. value
D C	PVC sheath, orange,-20~105℃, end with 8-pin connector	C	Min. value
12 - 13	For cable outlet: cable length, 01~99 meters	18 - 19	Non-usable area at head and end, customizable
10 - 13	For connector	S 4	40mm+60mm
P H 6 0	M16 male connector (6 pins)		
P B 8 0	M16 male connector (8 pins)		

**Note:** For supporting cables, please refer to Analog/Start-Stop Cable Accessories Selection

Note: The forward output of the sensor means that when the magnet ring moves away from the electronic bin, the output value increases and decreases when the magnet ring moves in the reverse direction.

Examples of selection: RB-M3600-S1-PH60-A01C-S4

Indication: The product is a compact sealed RB structure, with an effective stroke of 3600 mm, a bottom sealed M18×1.5, six-pin connector, output of 4-20 mA, Min. output value of no magnet ring state, single magnet ring, non-usable area of 40mm at the head and 60mm at the end.

# RB Flat Displacement Sensor

## X x Selection Guide-SSI

R	B	-	M					-			-					-	S						-		
01	02		03	04	05	06	07		08	09		10	11	12	13		14	15	16	17	18	19		20	21

### 01 - 02 Sensor shell form

R	B	Compact sealing installation
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### 03 - 07 Stroke length

Four digits, less than four digits are preceded by zero, M means metric system, unit mm

### 08 - 09 Installation form

S	1	Bottom seal
S	2	Middle seal
S	A	M18X1.5 measuring rod diameter 10mm, 304 material
S	B	M20X1.5 measuring rod diameter 10mm, 304 material

### 10 - 13 Connection form

### 10 - 11 For cable outlet

D	H	PUR sheath, orange,-20~90℃, end scattered, cable color 1
D	U	PVC sheath, orange,-20~105℃, end scattered, cable color 2
D	B	PVC sheath, orange,-20~105℃, end scattered, cable color 3
D	I	PUR sheath, orange,-20~90℃, end with 7-pin connector
D	V	PVC sheath, orange,-20~105℃, end with 7-pin connector
D	C	PVC sheath, orange,-20~105℃, end with 8-pin connector

### 12 - 13 For cable outlet: cable length, 01~99 meters

### 10 - 13 For connector

P	H	7	0	M16 male connector (7 pins)
P	B	8	0	M16 male connector (8 pins)

Note: See SSI cable fittings selection for supporting cables

### 14 - 19 Signal output mode

### 15 Data length

1	24bit	2	25bit	3	26bit*
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\* 26-bit are parity bits and 25-bit are status bits

### 16 Data format

B	Binary	G	Gray code
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### 17 Resolution

1	0.1mm	2	0.05mm
3	0.02mm	4	0.01mm
5	0.005mm	6	0.002mm
7	0.001mm	8	0.04mm

### 18 Direction

0	Forward	1	Reverse
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### 19 Mode

0	Regular
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### 20 - 21 Non-usable area at head and end, customizable

S	4	40mm+60mm
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# RB Flat Displacement Sensor

## X x Selection Guide-CAN Bus

R	B	-	M					-			-					-	C					-		
01	02		03	04	05	06	07		08	09		10	11	12	13		14	15	16	17	18		19	20

### 01 - 02 Sensor shell form

R	B	Compact sealing installation
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### 03 - 07 Stroke length

Four digits, less than four digits are preceded by zero, M means metric system, unit mm

### 08 - 09 Installation form

S	1	Bottom seal
S	2	Middle seal
S	A	M18X1.5 measuring rod diameter 10mm, 304 material
S	B	M20X1.5 measuring rod diameter 10mm, 304 material

### 10 - 13 Connection form

### 10 - 11 For cable outlet

D	A	PVC sheath, purple, 4 cores, -40℃~75℃, end scattered
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### 12 - 13 Straight-out cable mode: cable length, 01~99 meters

0	D	R	1	PVC sheath, length 150mm, end with 5-pin connector
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### 10 - 13 For connector

P	D	6	0	Set of 6-pin male connectors (M16)
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Note: For supporting cables, please refer to CAN bus cable fittings selection

### 14 - 18 Signal output mode

### 14 Interface

C	CAN bus
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### 15 Protocol type

1	CANopen	2	CANBasic
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### 16 Baud

1	1000kBit/s	2	800kBit/s
3	500kBit/s	4	250kBit/s
5	125kBit/s	6	100kBit/s
7	50kBit/s	8	20kBit/s

### 17 Resolution

1	0.1mm	2	0.05mm
3	0.02mm	4	0.01mm
5	0.005mm	6	0.002mm
7	0.001mm		

### 18 Number of magnet rings (1~9 optional)

### 19 - 20 Non-usable area at head and end, customizable

S	4	40mm+60mm
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